Implementing Distributed Consensus

🕁 Dan Lüdtke



What?

- My hobby project of learning about Distributed Consensus
 - I implemented a Paxos variant in Go and learned a lot about reaching consensus
 - A fine selection of some of the mistakes I made

Why?

- I wanted to understand Distributed Consensus
 - Everyone seemed to understand it. Except me.
- I am a hands-on person.
 - Doing \$stuff > Reading about \$stuff

Why talk about it?

• Knowledge sharing

Distributed Consensus

Protocols

• Paxos

- Multi-Paxos
- Cheap Paxos
- Raft



- ZooKeeper Atomic Broadcast
- Proof-of-Work Systems
 - Bitcoin
- Lockstep Anti-Cheating



Implementations

- Chubby
 - coarse grained lock service
- etcd
 - a distributed key value store

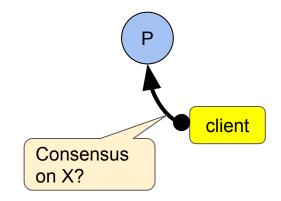


- Apache ZooKeeper
 - a centralized service for
- maintaining configuration information, naming, providing distributed synchronization

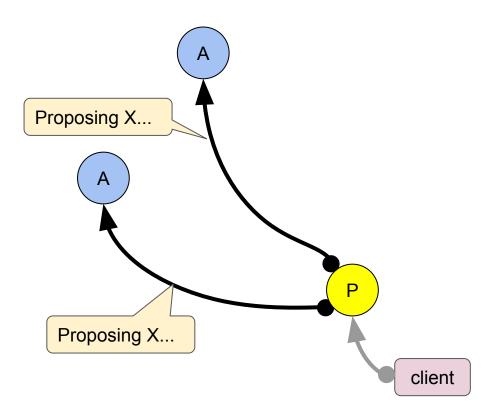
Paxos

• Client

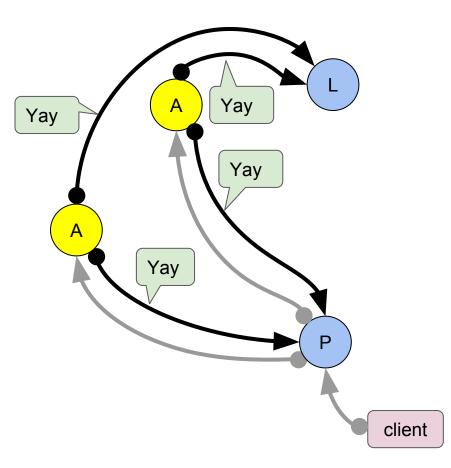
- Issues request to a *proposer*
- Waits for response from a *learner*
 - Consensus on value X
 - No consensus on value X
- Acceptor
- Proposer
- Learner
- Leader



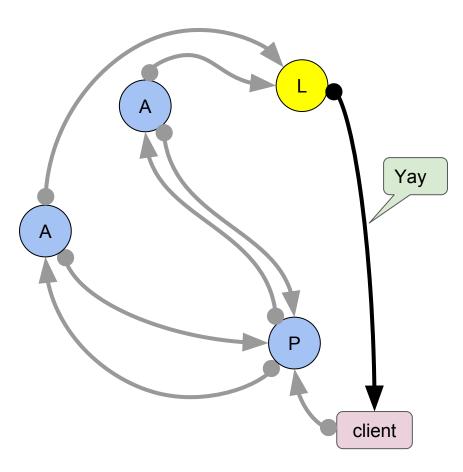
- Client
- Proposer (P)
 - Advocates a *client* request
 - Asks acceptors to agree on the proposed value
 - Move the protocol forward when there is conflict
- Acceptor
- Learner
- Leader



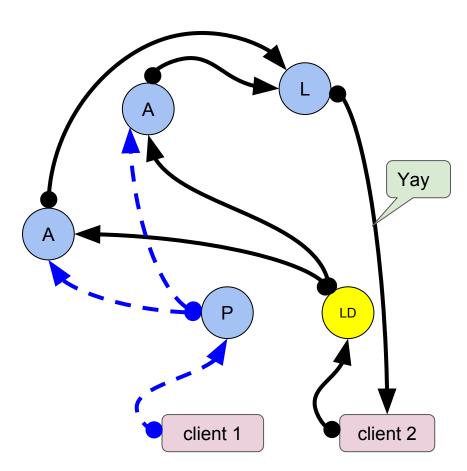
- Client
- Proposer (P)
- Acceptor (A)
 - Also called "voter"
 - The Fault-tolerant "memory" of the system
 - Groups of acceptors form a *quorum*
- Learner
- Leader



- Client
- Proposer (P)
- Acceptor (A)
- Learner (L)
 - Adds replication to the protocol
 - Takes action on learned (agreed on) values
 - E.g. respond to *client*
- Leader

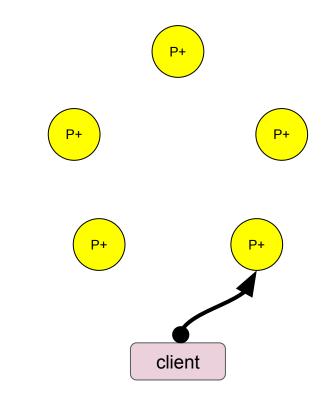


- Client
- Proposer (P)
- Acceptor (A)
- Learner (L)
- Leader (LD)
 - Distinguished proposer
 - The only *proposer* that can make progress
 - Multiple *proposers* may believe to be leader
 - Acceptors decide which one gets a majority



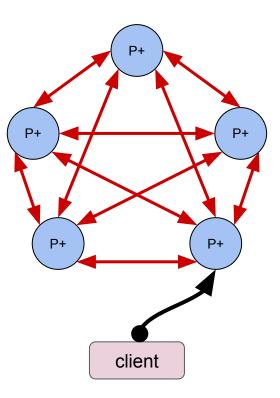
Coalesced Roles

- A single processors can have multiple roles
- P+
 - Proposer
 - Acceptor
 - Learner
- Client talks to any processor
 - Nearest one?
 - Leader?



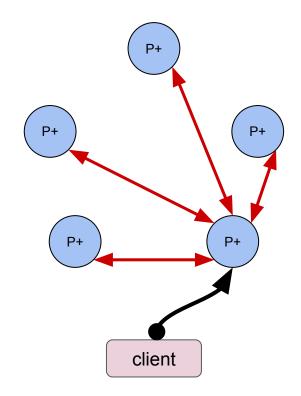
Coalesced Roles at Scale

- P+ system is a complete digraph
 - a directed graph in which every pair of distinct vertices is connected by a pair of unique edges
 - Everyone talks to everyone
- Let n be the number of processors
 a.k.a. Quorum Size
- **Connections = n** * (**n** 1)
 - Potential network (TCP) connections

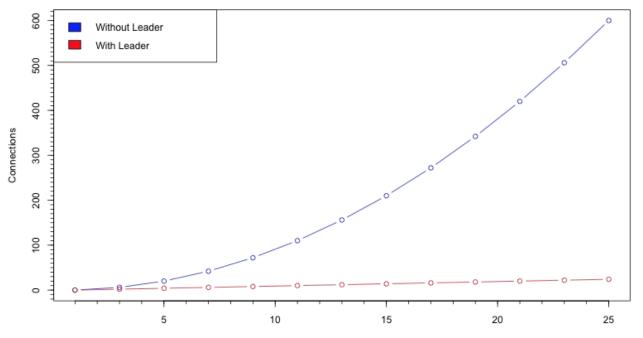


Coalesced Roles with Leader

- P+ system with a leader is a directed graph
 - Leader talks to everyone else
- Let n be the number of processors
 a.k.a. Quorum Size
- Connections = n 1
 - Network (TCP) connections



Coalesced Roles at Scale



Quorum Size

Limitations

- Single consensus
 - Once consensus has been reached no more progress can be made
 - But: Applications can start new Paxos runs
- Multiple proposers may believe to be the leader
 - dueling proposers
 - theoretically infinite duell
 - practically retry-limits and jitter helps
- Standard Paxos not resilient against Byzantine failures
 - Byzantine: Lying or compromised processors
 - Solution: Byzantine Paxos Protocol



Introducing Paxos-based

- Feature-free
- Educational
- Lock Service



Skinny "Features"

- Easy to understand and observe
- Coalesced Roles
- Single Lock
 - Locks are always advisory!
 - A lock service does not enforce obedience to locks.
- Go
- Protocol Buffers
- gRPC
- Do not use in production!



Assuming...

- Oregon
 - North America
- São Paulo
 - South America
- London
 - Europe
- Taiwan
 - o Asia
- Sydney
 - Australia



How Skinny reaches consensus

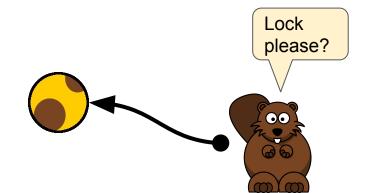
SKINNY QUORUM

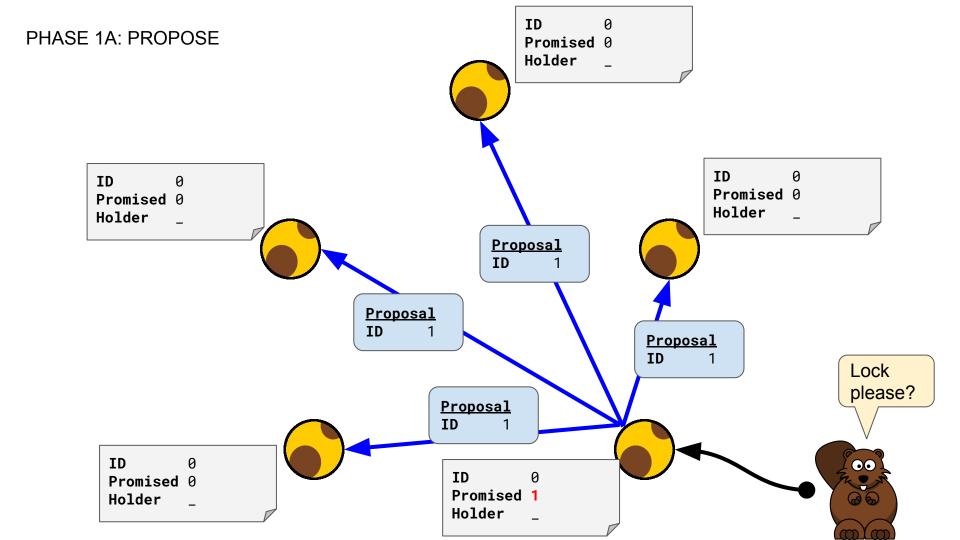


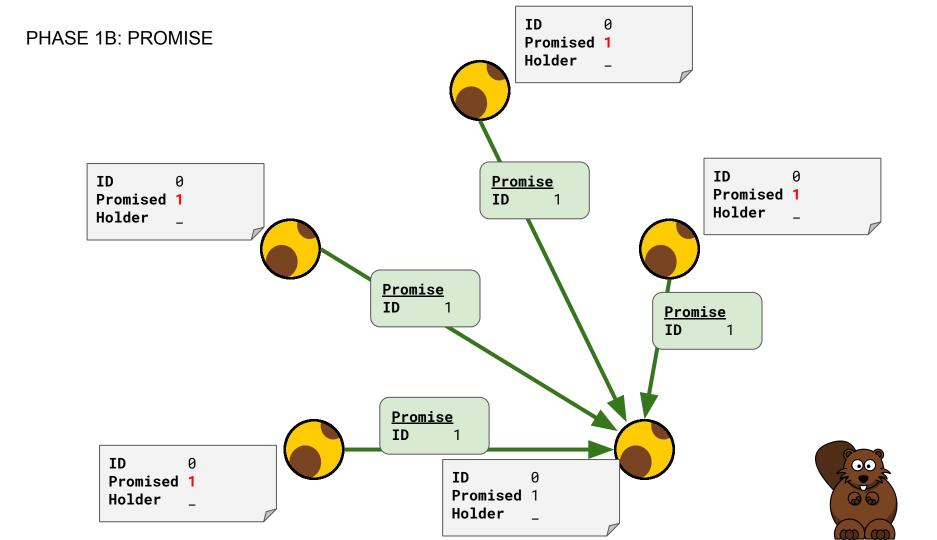


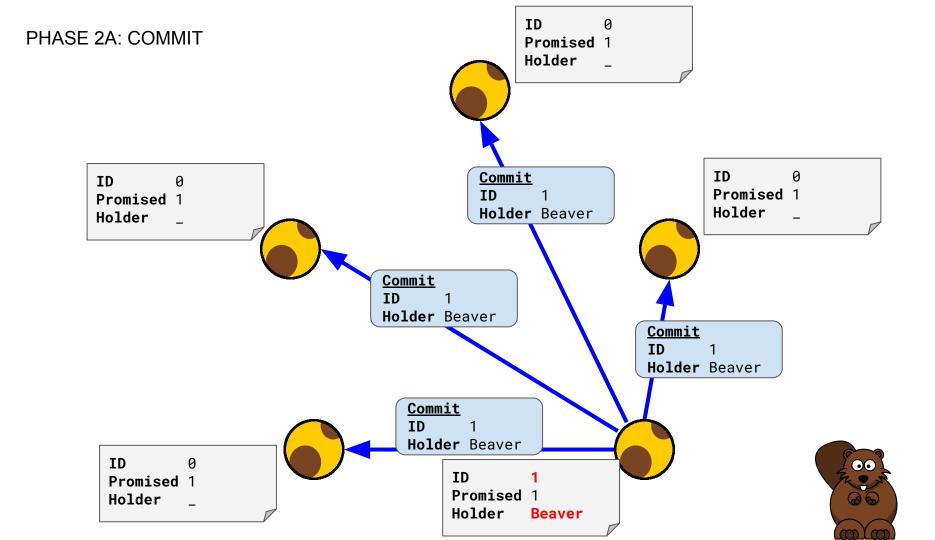


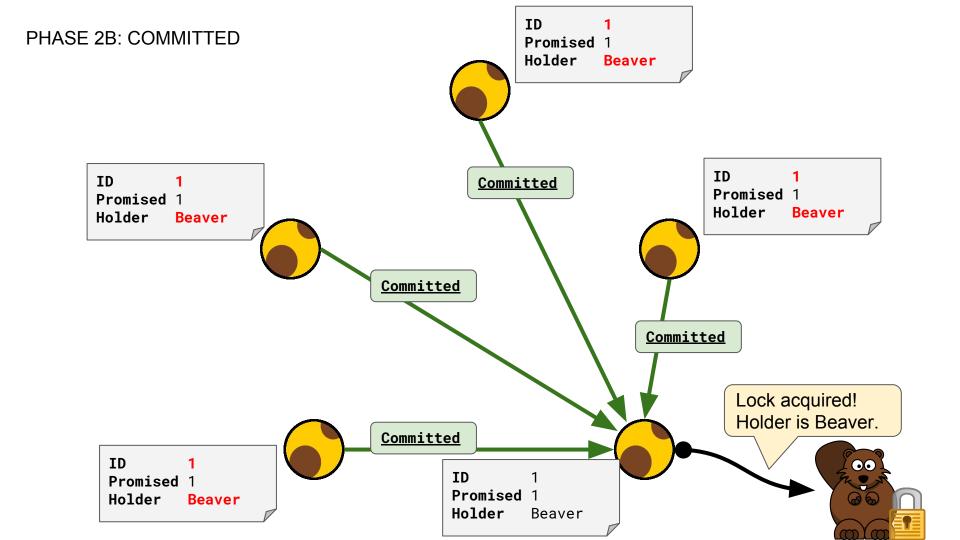




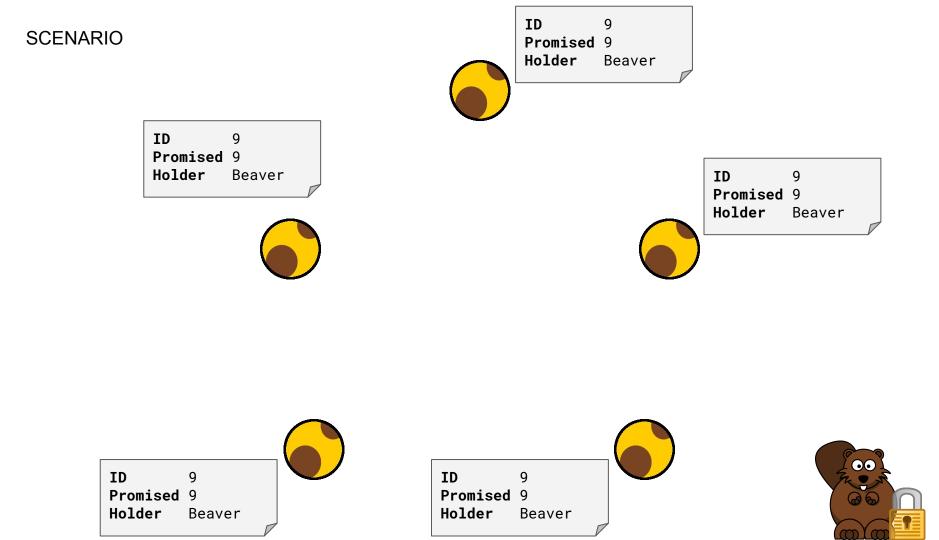


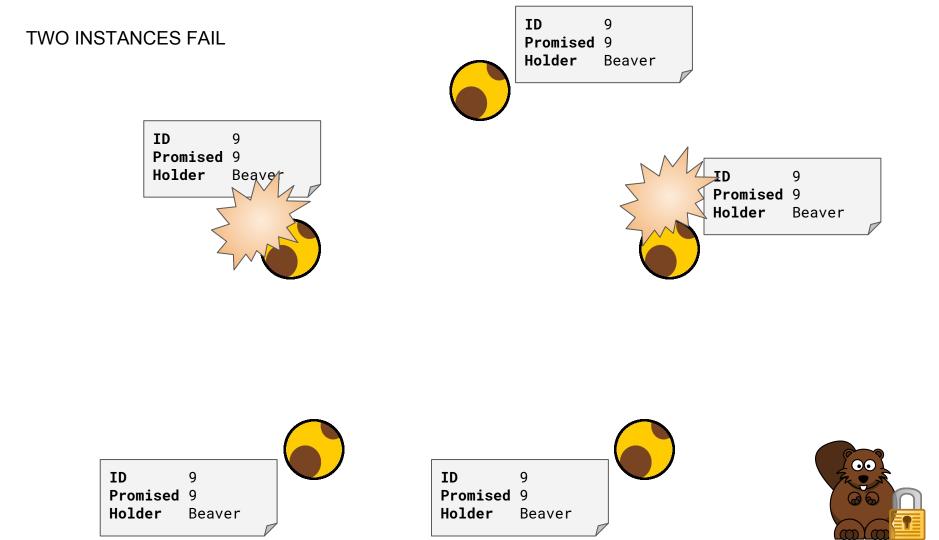


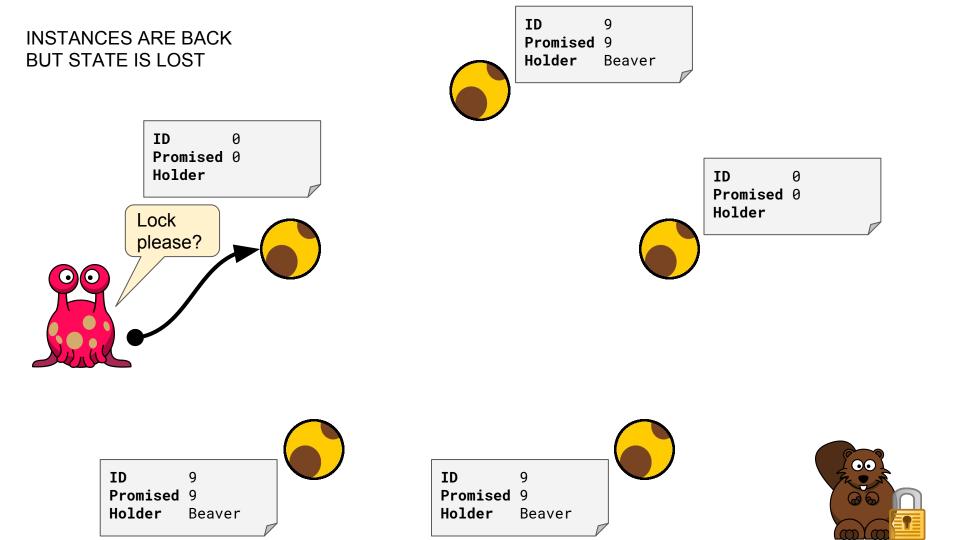


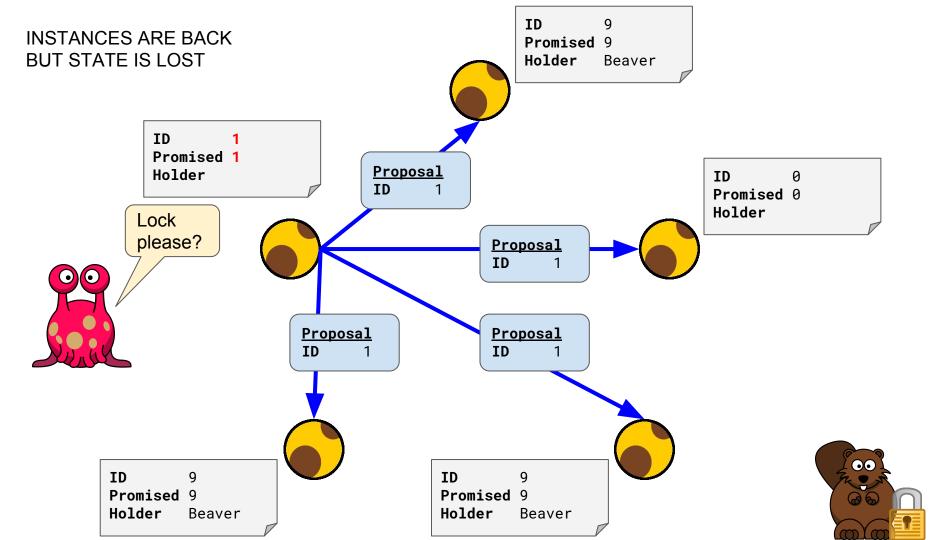


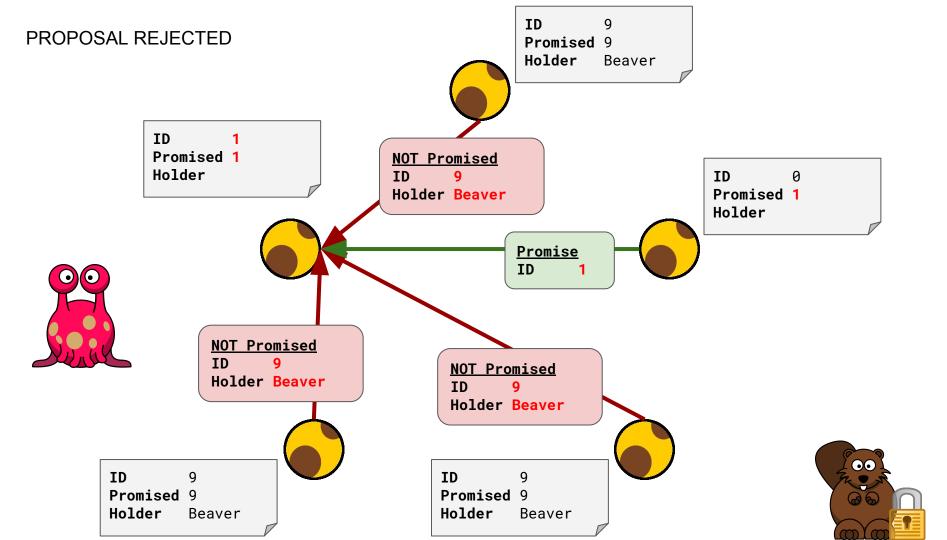
How Skinny deals with Instance Failure

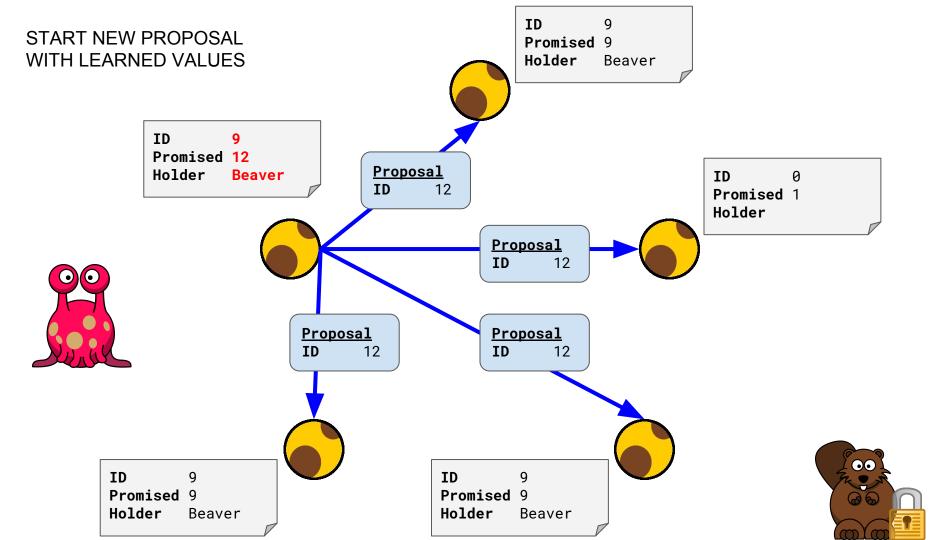


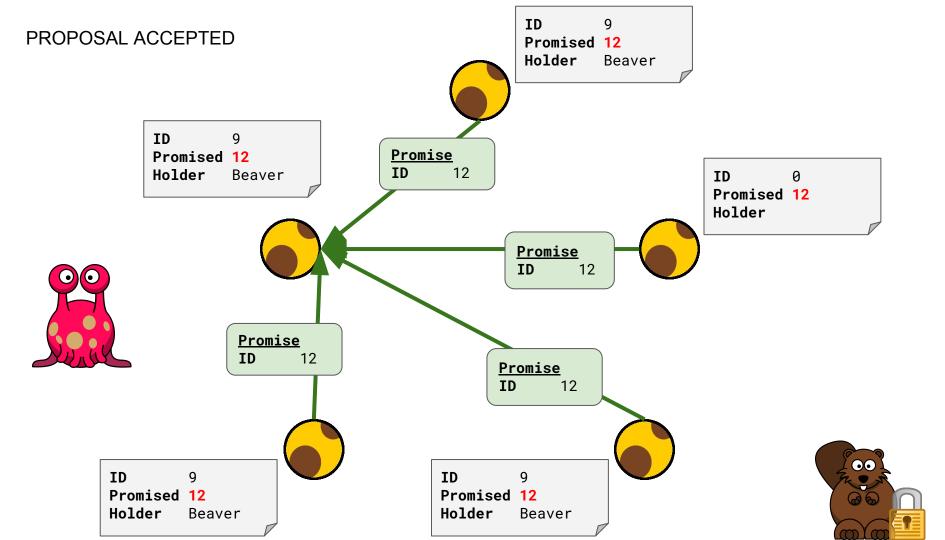


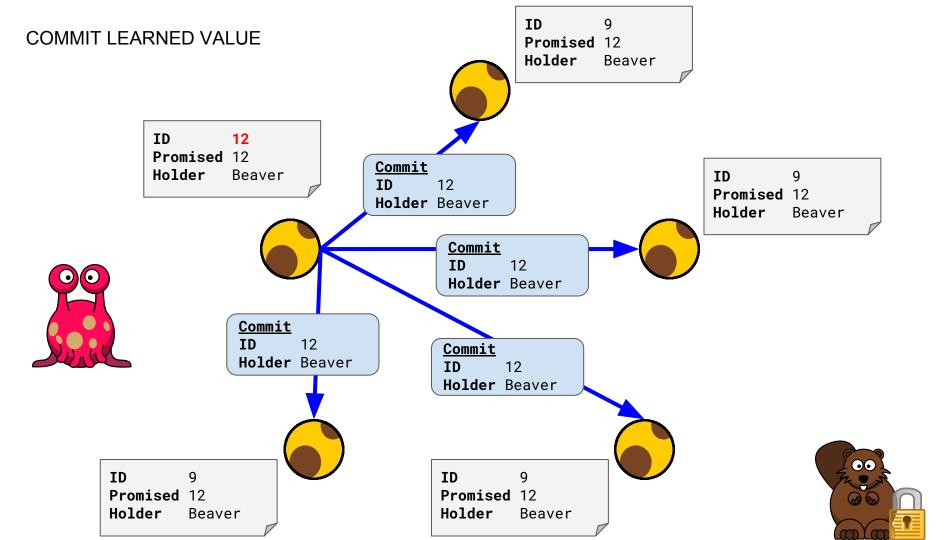


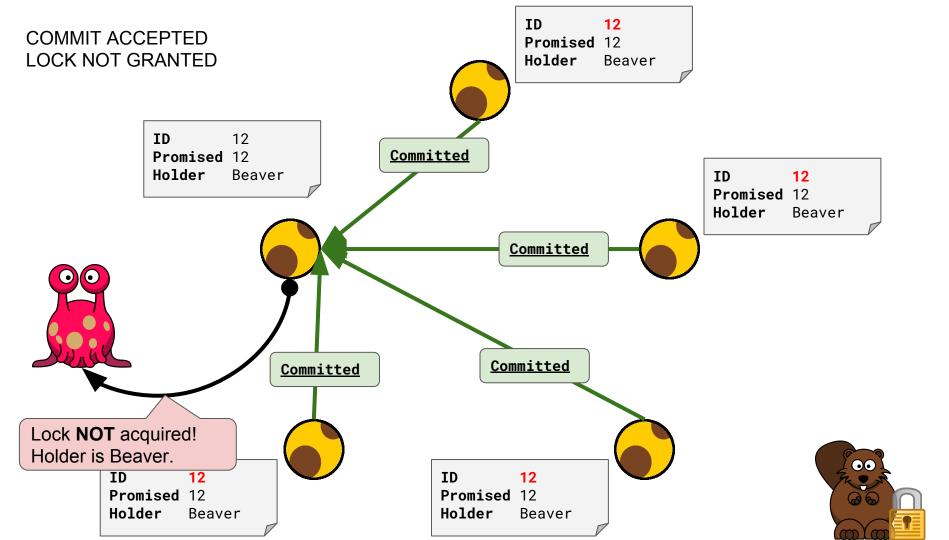








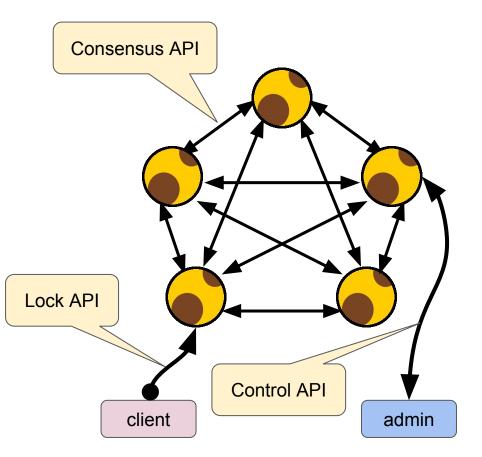




Skinny APIs

Skinny APIs

- Lock API
 - Used by clients to acquire or release a lock
- Consensus API
 - Used by Skinny instances to reach consensus
- Control API
 - Used by us to observe what's happening



Lock API

```
message AcquireRequest {
```

```
string Holder = 1;
```

```
message AcquireResponse {
```

```
bool Acquired = 1;
```

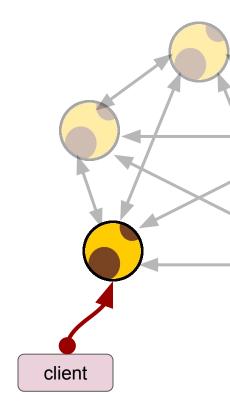
```
string Holder = 2;
```

message ReleaseRequest {}
message ReleaseResponse {
 bool Released = 1;

service Lock {

```
rpc Acquire(AcquireRequest) returns (AcquireResponse);
```

```
rpc Release(ReleaseRequest) returns (ReleaseResponse);
```



Consensus API

```
// Phase 1: Promise
message PromiseRequest {
    uint64 ID = 1;
}
message PromiseResponse {
    bool Promised = 1;
    uint64 ID = 2;
```

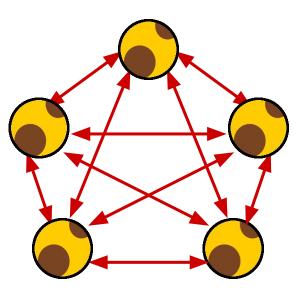
string Holder = 3;

```
// Phase 2: Commit
message CommitRequest {
    uint64 ID = 1;
    string Holder = 2;
}
```

```
message CommitResponse {
    bool Committed = 1;
```

service Consensus {

rpc Promise (PromiseRequest) returns (PromiseResponse); rpc Commit (CommitRequest) returns (CommitResponse);

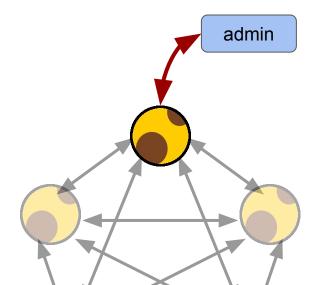


Control API

```
message StatusRequest {}
message StatusResponse {
   string Name = 1;
   uint64 Increment = 2;
   string Timeout = 3;
   uint64 Promised = 4;
   uint64 ID = 5;
   string Holder = 6;
   message Peer {
       string Name = 1;
       string Address = 2;
   repeated Peer Peers = 7;
```

service Control {

rpc Status(StatusRequest) returns (StatusResponse);



My Stupid Mistakes My Awesome Learning Opportunities

Reaching Out...

Skinny Instance

- List of peers
 - All other instances in the quorum
- Peer
 - gRPC Client Connection
 - Consensus API Client

// Instance represents a skinny instance type Instance struct { mu sync.RWMutex // begin protected fields []*peer peers // end protected fields type peer struct { string name address string *grpc.ClientConn conn client pb.ConsensusClient

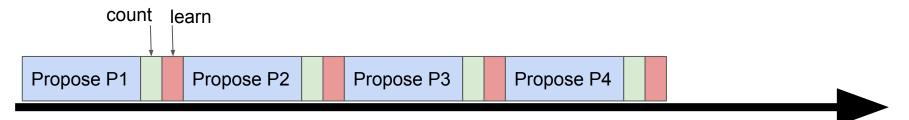
Propose Function

- 1. Send proposal to all peers -
- 2. Count responses
 - Promises
- 3. Learn previous consensus (if any)

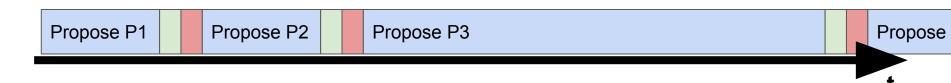
```
for _, p := range in.peers {
    // send proposal
    resp, err := p.client.Promise(
        context.Background(),
        &pb.PromiseRequest{ID: proposal})
    if err != nil {
        continue
       resp.Promised {
    1†
        yay++
    }
    learn(resp)
```

Resulting Behavior

- Sequentiell Requests
- Waiting for IO

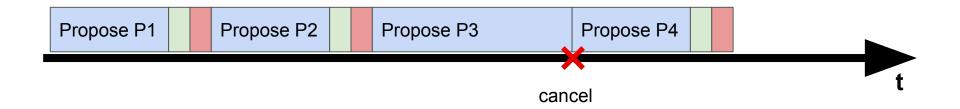


• Instance slow or down...?



Improvement #1

• Limit the Waiting for IO



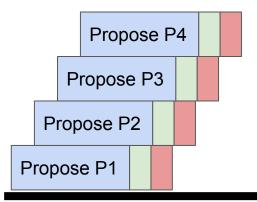
Timeouts

- This example • Hardcoded
- Actual
 - From Configuration

```
for _, p := range in.peers {
    // send proposal
    ctx, cancel := context.WithTimeout(
        context.Background(),
        time.Second*3)
    resp, err := p.client.Promise(ctx,
        &pb.PromiseRequest{ID: proposal})
    cancel() // prevent context leak
    if err != nil {
        continue
    }
    if resp.Promised {
        yay++
    }
    learn(resp)
```

Improvement #2 (Idea)

• Parallel Requests



• What's wrong?

Improvement #2 (Corrected)

- Parallel Requests
- Synchronized Counting
- Synchronized Learning

	Propose P4			4				
	Propose P3							
	Ρ	Propose P2						
Propose P1								

Parallelism

- Goroutine!
- Context with timeout
- But how to handle success?

```
for _, p := range in.peers {
    // send proposal
    go func(p *peer) {
        ctx, cancel := context.WithTimeout(
            context.Background(),
            time.Second*3)
        defer cancel()
```

```
resp, err := p.client.Promise(ctx,
    &pb.PromiseRequest{ID: proposal})
if err != nil { return }
```

```
// now what?
}(p)
```

Synchronizing

• Channels to the rescue!

type response struct { from string promised bool id uint64 holder string responses := make(chan *response) for _, p := range in.peers { go func(p *peer) { responses <- &response{</pre> from: p.name, promised: resp.Promised, id: resp.ID, holder: resp.Holder, }(p)

Synchronizing

- Counting
- yay := 1
 - Because we always vote for ourselves
- Learning

// count the votes yay, nay := 1, 0 for r := range responses { // count the promises if r.promised { yay++ } else { nay++ } in.learn(r) }

What's wrong?

- We never close the channel
- range is blocking forever

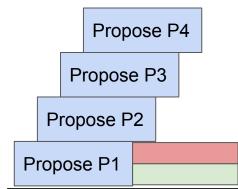
```
responses := make(chan *response)
for _, p := range in.peers {
    go func(p *peer) {
        . . .
        responses <- &response{...}</pre>
    }(p)
// count the votes
yay, nay := 1, 0
for r := range responses {
     // count the promises
     . . .
     in.learn(r)
```

More synchronizing

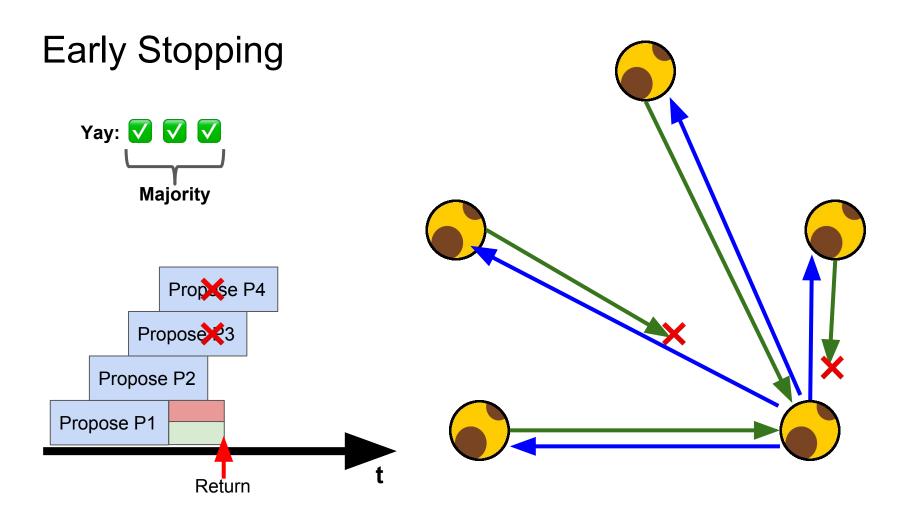
- Use Waitgroup
- Close Channel when all requests are done

```
responses := make(chan *response)
wg := sync.WaitGroup{}
for _, p := range in.peers {
    wg.Add(1)
    go func(p *peer) {
        defer wg.Done()
         . . .
        responses <- &response{...}</pre>
    }(p)
   close responses channel
go func() {
    wg.Wait()
    close(responses)
}()
   count the promises
for r := range responses {...}
```

Result



Ignorance Is Bliss?



Early Stopping (1)

- One context for all outgoing promises
- We cancel as soon as we have a majority
- We always cancel before leaving the function to prevent a context leak

```
type response struct {
   from string
   promised bool
   id uint64
   holder string
```

```
responses := make(chan *response)
```

```
ctx, cancel := context.WithTimeout(
    context.Background(),
    time.Second*3)
```

defer cancel()

Early Stopping (2)

• Nothing new here

```
wg := sync.WaitGroup{}
for _, p := range in.peers {
    wg.Add(1)
    go func(p *peer) {
        defer wg.Done()
```

resp, err := p.client.Promise(ctx, &pb.PromiseRequest{ID: proposal}) ... // ERROR HANDLING. SEE NEXT SLIDE!

responses <- &response{
 from: p.name,
 promised: resp.Promised,
 id: resp.ID,
 holder: resp.Holder,</pre>

}(p)

Early Stopping (3)

- We don't care about cancelled requests
- We want errors which are **not** the result of a canceled proposal to be counted as a **negative answer** (nay) later.
- For that we emit an **empty response** into the channel in those cases.

resp, err := p.client.Promise(ctx, &pb.PromiseRequest{ID: proposal})

if err != nil { if ctx.Err() == context.Canceled { return } responses <- &response{from: p.name} return }</pre>

responses <- &response{...}</pre>

. . .

Early Stopping (4)

 Close responses channel once all responses have been received, failed, or canceled go func() {
 wg.Wait()
 close(responses)
}()

Early Stopping (5)

- Count the votes
- Learn previous consensus (if any)
- Cancel all in-flight proposal if we have reached a majority

```
yay, nay := 1, 0
canceled := false
for r := range responses {
    if r.promised { yay++ } else { nay++ }
```

```
in.learn(r)
```

```
if !canceled {
    if in.isMajority(yay) || in.isMajority(nay) {
        cancel()
        canceled = true
```

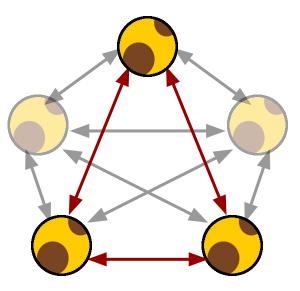
Is this fine?

- Timeouts are now even more critical!
- "Ghost Quorum" Effect
- Let's all agree to disagree!
- Idea: Use different timeouts in propose() and commit()?



Ghost Quorum

- Reason: Too tight timeout
- Some instances always time out
 - Effectively: Quorum of remaining instances
- Hidden reliability risk!
 - If one of the remaining instances fails, the distributed lock service is down!
 - No majority
 - No consensus



The Duell

What's wrong?

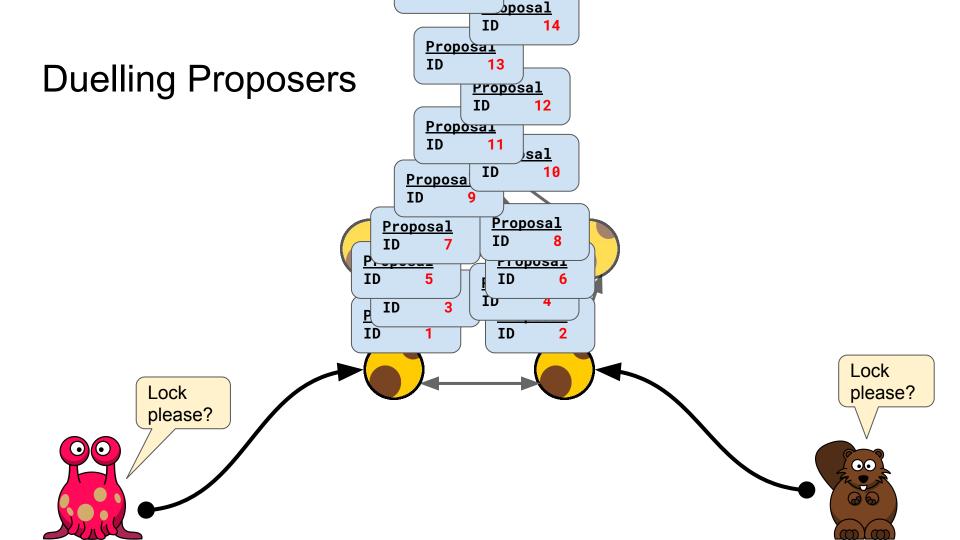
- Retry Logic
 - Unlimited retries!
- Coding Style
 - I should care about the return value.

func foo(...) error { • • • retry: promised := in.propose(newID) if !promised { in.log.Printf("retry (%v)", id) goto retry

_ = in.commit(newID, newHolder)

return nil

• • •



Soon...

NAME london oregon spaulo sydney taiwan	5	1062520	ID 1062520 1062520 1062520	HOLDER 	LAST SEEN now connection error connection error 2 seconds ago 1 second ago
--	---	---------	-------------------------------------	----------------	---

Instances **oregon** and **spaulo** were intentionally offline for a different experiment

The Fix

Retry Counter

X Backoff

X Jitter

```
func foo(...) error {
    retries := 0
retry:
    promised := in.propose(newID)
    if !promised {
        if retries < 3 {</pre>
             retries++
             in.log.Printf("retry (%v)", id)
             goto retry
     . . .
    return nil
```

Demo Time!

Further Reading

Reaching Agreement in the Presence of Faults

M. PEASE, R. SHOSTAK, AND L. LAMPORT

SRI International, Menlo Park, California

ABSTRACT. The problem addressed here concerns a set of isolated processors, some unknown subset of which may be faulty, that communicate only by means of two-party messages. Each nonfaulty processor has a private value of information that must be communicated to each other nonfaulty processor. Nonfaulty processors always communicate honestly, whereas faulty processors may lie The problem is to devise an algorithm in which processors communicate their own values and relay values received from others that allows each nonfaulty processor to infer a value for each other processor. The value inferred for a nonfaulty processor must be that processor's private value, and the value inferred for a faulty one must be consistent with the corresponding value

https://lamport.azurewebsites.net/pubs/reaching.pdf

Further Reading

The Chubby lock service for loosely-coupled distributed systems

Mike Burrows, Google Inc.

Naming of "Skinny" absolutely not inspired by "Chubby" ;)

W the our experiences with the Chubby lock serwhich is intended to provide coarse-grained lockoo s well as reliable (though low-volume) storage for osely-coupled distributed system. Chubby provides in face much like a distributed file system with adcks, but the design emphasis is on availability liability as opposed to high performance. Many example, the Google File System [7] uses a Chubby lock to appoint a GFS master server, and Bigtable [3] uses Chubby in several ways: to elect a master, to allow the master to discover the servers it controls, and to permit clients to find the master. In addition, both GFS and Bigtable use Chubby as a well-known and available location to store a small amount of meta-data; in effect they use Chubby as the root of their distributed data struc-

https://research.google.com/archive/chubby-osdi06.pdf

Further Watching



Paxos Agreement - Computerphile

Heidi Howard University of Cambridge Computer Laboratory https://youtu.be/s8JqcZtvnsM



The Paxos Algorithm Luis Quesada Torres Google Site Reliability Engineering https://youtu.be/d7nAGI_NZPk



Try, Play, Learn!

github.com/danrl/skinny

- The Skinny Lock Server is open source software!
 - skinnyd lock server
 - **skinnyctl** control utility
- Terraform modules Y Terraform
 - To get you started quickly with the infrastructure
- Ansible playbooks
 - To help you install and configure your **skinnyd** instances

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